To Section 5.2

(c) To Compute Turning Points, [Keener73] and [MooreB] have proposed *augmented ac*companying systems. The first one reads:

$$\Phi_1(z) := \Phi_1(\mu, x, u) := \begin{bmatrix} F(\mu, x) \\ F_x(\mu, x)u \\ a u - 1 \end{bmatrix} = 0, \quad z = (\mu, x, u), \ a \in \mathcal{E}_d \text{ fixed } .$$
(1)

Lemma 1 Let (μ_0, x_0) be a turning point and $a u_1 = 1$. Then $\Phi_1(z_0) = \Phi_1(\mu_0, x_0, u_1) = 0$ and

grad
$$\Phi_1(z_0) : \mathbb{R} \times \mathcal{E} \times \mathcal{E} \to \mathcal{F} \times \mathcal{F} \times \mathbb{R}$$

has a bounded inverse if and only if

$$v^1 F^0_{xx} \langle u_1, u_1 \rangle \neq 0.$$
⁽²⁾

Proof. Cf. [MooreB]. We show that $[\Phi_1]_z(z_0)$ is bijective iff (2) holds. Then the assertion follows from the Inverse Operator Theorem because $[\Phi_1]_z(z^0)$ is bounded and linear. Let

 $z = (\sigma, z_1, z_2) \in \mathbb{R} \times \mathcal{E} \times \mathcal{E}, \quad g = (g_1, g_2, \tau) \in \mathcal{F} \times \mathcal{F} \times \mathbb{R}$

and consider the linear system

$$[\Phi_1]_z(z_0)z = g, \ z_0 = (\mu_0, x_0, u),.$$

An expansion of this equation yields

$$F^0_{\mu}\sigma + F^0_x z_1 = g_1, \tag{3}$$

$$F_{x\mu}^{0}u_{1}\sigma + F_{xx}^{0}\langle u_{1}, z_{1}\rangle + F_{x}^{0}z_{2} = g_{2}, \qquad (4)$$

$$az_2 = \tau. \tag{5}$$

In order to show that z_1 and z_2 are determined uniquely, we can choose an arbitrary but fixed decomposition of the space \mathcal{E} . We use a decomposition defined by a and write

$$z_1 = \alpha u_1 + w, \quad a w = 0, z_2 = \beta u_1 + q, \quad a q = 0,$$
(6)

and show that σ , α , β , w, and q are determined uniquely. From (3) we obtain

$$\sigma = v^1 g_1 / v^1 F^0_\mu$$

because $v^1 F_x^0 = 0$, and w is the unique solution of

$$F_x^0 w = g_1 - F_\mu^0 \sigma, \ a w = 0.$$

Insertion of σ and z_1 into (4) yields

$$F_x^0(\beta u_1 + q) = g_2 - F_{x\mu}^0 u_1 \sigma - F_{xx}^0 \langle u_1, \alpha u_1 + w \rangle =: b.$$
(7)

 $\mathbf{2}$

The solvability condition $v^1b = 0$ yields a unique value for α iff $v^1F_{xx}^0\langle u_1, u_1\rangle \neq 0$. Then q is the unique solution of (6) satisfying a q = 0. Finally, β is determined uniquely from the condition

$$a(\beta u_1 + q) = \beta a u_1 = \tau.$$

because $a u_1 \neq 0$ by assumption.

Conversely, a regular solution of (1) is a quadratic turning point if in addition dim Ker $F_x^0 = 1$ and $v^1 F_\mu^0 \neq 0$ which is fulfilled in normal case. Besides, the inequality $v^1 F_\mu^0 \neq 0$ is much more often fulfilled as the equality $v^1 F_\mu^0 = 0$.

Accordingly, for a test on possible turning points, NEWTON' method may be applied to solve $\Phi_1(z) = 0$. Note however that the result is a necessary condition and the defining properties of a turning point have to be verified after computation.

The second accompanying system is dual to the first system (1) in some way:

$$\Phi_2(z) := \Phi_2(\mu, x, v) := \begin{bmatrix} F(\mu, x) \\ v F_x(\mu, x) \\ v F_\mu(\mu, x) - 1 \end{bmatrix} = 0, \ z = (\mu, x, v), \ v \in \mathcal{F}_d \quad .$$
(8)

Lemma 2 Let (μ_0, x_0) be a turning point. Then $\Phi_2(z_0) = \Phi_2(\mu_0, x_0, v^1) = 0$ and

grad $\Phi_2(z_0) : \mathbb{R} \times \mathcal{E} \times \mathcal{F}_d \to \mathcal{F} \times \mathcal{E}_d \times \mathbb{R}$

has a bounded inverse if and only if (2) does hold.

Proof. Let

$$z = (\sigma, z_1, z^2) \in \mathbb{R} \times \mathcal{E} \times \mathcal{F}_d, \ g = (g_1, g^2, \tau) \in \mathcal{F} \times \mathcal{E}_d \times \mathbb{R}.$$

Then we have to show again that the linear system

 $[\Phi_2]_z(z_0)z = g, \ z_0 = (\mu_0, x_0, v^1),$

has a unique solution z for every g. An expansion of this equation yields

$$F^{0}{}_{\mu}\sigma + F^{0}{}_{x}z_{1} = g_{1}, \tag{9}$$

$$v^{1}F^{0}{}_{x\mu}\sigma + v^{1}F^{0}{}_{xx}z_{1} + z^{2}F^{0}_{x} = g^{2}, \qquad (10)$$

$$z^2 F_x^0 = \tau. \tag{11}$$

We use again a suitable decomposition of \mathcal{E} and \mathcal{F}_d and write

$$z_1 = \alpha u_1 + w, \quad v^1 w = 0, z^2 = \beta v^1 + q, \quad q \, u_1 = 0.$$
(12)

Then we have to show that σ, α, β, w , and q are determined uniquely. From (9) we get

$$\sigma = v^1 g_1$$

because $v^1 F_x^0 = 0$ and w is the unique solution of

$$F^{0}{}_{x}w = g_1 - F^{0}{}_{\mu}\sigma, \ v^1w = 0,$$

again. Substitution of σ and (12) into (10) yields

$$(\beta v^{1} + q)F^{0}{}_{x} = g^{2} - v^{1}F^{0}{}_{x\mu}\sigma - v^{1}F^{0}{}_{xx}(\alpha u_{1} + w) =: b.$$
(13)

The solvability condition $b u_1 = 0$ yields a unique value α iff $v^1 F_{xx}^0 \langle u_1, u_1 \rangle \neq 0$. Then q is the unique solution of (13) satisfying $q u_1 = 0$. Finally, β is determined again uniquely from the condition (11),

$$(\beta v^1 + q)F^0{}_\mu = \tau,$$

because $v^1 F^0{}_\mu \neq 0$.